

Faculty of Mechanical Engineering

B.E. Robotics and Automation

(R 2021) Semester – II

| Course Code: BE3273 | | |
|--|--|--|
| Course Title: Basic Electrical, Electronics Engineering and Measurements Laboratory | | |
| Sl. No. | Description of Equipment | Required numbers (for batch of 30 students) |
| 1 | Verification of ohms and Kirchhoff's Laws 1. DC Regulated Power supply (0 - 30 V variable) 2. Bread Board 3. Resistors 4. Multimeter 5. Connecting wires | 1 1 As per Circuit diagram 1 As Required |
| 2 | Load test on DC Shunt Motor. 1. Ammeter MC (0-20A) 2. Voltmeter MC (0-300)V 3. Rheostat 7.5 Ω, 10 A 4. Tachometer 5. Field Rheostat 175 Ω, 1.5 A 6. Connecting wires | 1 1 1 1 1 As Required |
| 3 | Load test on Self Excited DC Generator 1. DC shunt generator(0- 300V) 2. Ammeter (0-30 A), (0-2A) 3. Voltmeter (0-30V) 4. Rheostat 175Ω, 250 Ω 5. Tachometer 6. Connecting Wires | 1 1 1 1 1 As Required |
| 4 | Load test on Single phase Transformer 1. Ammeter (0-30) A, (0-5) A 2. Voltmeter (0-150)V, (0-300)V 3. Wattmeter – 300V, 5A, UPF 4. Autotransformer 5. Single phase Transformer 6. Connecting wires | 1 1 1 1 1 As Required |
| 5 | Load Test on Induction Motor 1. Ammeter MI (0-20A) 2. Voltmeter MI (0-300)V 3. Wattmeter – 300V, 30 A 4. Tachometer – Digital 5. Connecting Wires – As Required 6. Single phase Induction motor | 1 1 1 1 As Required 1 |
| 6 | A. Experiment on Transistor based application circuits (Inverting and non-inverting amplifier or switching circuits) 1. Transistor (No-BC107) 2. Resistors- 2.2kΩ, 47KΩ, 10KΩ, 560Ω 3. Capacitors - 10μF, 3.3μF, 22μF 4.. Bread Board 5. DC Regulated Power supply (0 - 30 V variable) | 1 1 1 1 1 |

| | | |
|-------|--|---|
| | 5. CRO 6. Connecting wires B. Experiments on Operational Amplifier based Inverting and non-inverting amplifier 1. Function Generator 1 KHz 2. CRO 20 MHz 3. Dual RPS 0 – 30 V 4. Op-Amp IC 741 5. Resistors R1= 100 Ω and RF= 1.5 K Ω 6. Connecting wires | 1 As Required 1 1 1 1 As Required |
| 7. | Experiments on ADC 1. Resistors – 10 K Ω 2. Resistors - 220 Ω 2. Capacitor – 150 μ F, 10 μ F 3. ADC -0804 4. Bread Board 5. Connecting wires 6. Dual RPS (0 – 30) V | 2 8 1 1 1 As Required 1 |
| 8, | Experiments on 555 timer 1. IC 555 Timer 2. Resistor R1, R2 47k Ω , 1k Ω 3. Resistor R4 220 Ω Load 4. Capacitor, C1 10 μ F 5. Capacitor, C2 0.01 μ F 6. Bread Board 7. Connecting wires 8. CRO 20 MHz 9. RPS (0 – 30) V | 1 1 1 1 1 1 As Required 1 1 |
| 9,10. | Study on function of DSO. Measurement of Amplitude, Frequency, Time, Phase Measurement using DSO 1. DSO | 1 |

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(R 2021) Semester – III

MR3361 ELECTRICAL DRIVES AND ACTUATORS LABORATORY

| Sl.No. | Description of Equipment | Required Numbers |
|---------------|---|-------------------------|
| 1. | DC Motor with load | 1 |
| 2. | 3 Phase Induction Motor with load | 1 |
| 3. | 3 Phase Synchronous Motor with load | 1 |
| 4. | Rheostat based Speed control of motors (AC and DC) with load | 1 |
| 5. | MOSFET, IGBT, SCR and TRIAC | 1 |
| 6. | DC motor with speed control Drive | 1 |
| 7. | DC servomotor with Power Electronic Drive (Position, Direction and speed). | 1 |
| 8. | BLDC and PMDC motors with Power Electronic Drive (Position, Direction and speed). | 1 |
| 9. | Stepper Motor with Power Electronic Drive (Position, Direction and speed). | 1 |
| 10. | Three-phase Induction Motor with Power Electronic Drive. | 1 |
| 11. | VFD with single phase and three-phase induction motor. | 1 |
| 12. | AC servomotor with Power Electronic Drive (Position, Direction and speed). | 1 |
| 13. | Tachometers, voltmeters, ammeters and multimeters | Each 5 |

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(R 2021) Semester – III

RA3311 ROBOT MODELLING AND SIMULATION LABORATORY

| Sl.No. | Description of Equipment | Required Numbers |
|---------------|--|-------------------------|
| 1 | Computers | 15 |
| 2 | CAD modelling packages – open source/ licensed | 15 |

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(R 2021) Semester – IV

MR3452 CONTROL SYSTEMS ENGINEERING (LABORATORY)

| Sl.No. | Description of Equipment | Required Numbers |
|---------------|---|-------------------------|
| 1. | Computer -15 No's | Each -1 |
| 2. | MATLAB licenced / SCILAB open source with control system toolbox installed on above computers | 15 |

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(R 2021) Semester – IV

ME3382 MANUFACTURING TECHNOLOGY LABORATORY

LIST OF EQUIPMENT FOR BATCH OF 30 STUDENTS

| S.No. | NAME OF THE EQUIPMENT | Required Numbers |
|--------------|--|-------------------------|
| 1. | Centre Lathes | 7 Nos. |
| 2. | Shaper | 1 No. |
| 3. | Horizontal Milling Machine | 1 No. |
| 4. | Vertical Milling Machine | 1 No. |
| 5. | Surface Grinding Machine | 1 No. |
| 6. | Cylindrical Grinding Machine | 1 No. |
| 7. | Radial Drilling Machine | 1 No. |
| 8. | Lathe Tool Dynamometer | 1 No. |
| 9. | Milling Tool Dynamometer | 1 No. |
| 10. | Gear Hobbing Machine | 1 No. |
| 11. | Gear Shaping Machine | 1 No. |
| 12. | Arc welding transformer with cables and holders | 2 Nos. |
| 13. | Oxygen and Acetylene gas cylinders, blow pipe and other welding outfit | 1 No. |
| 14. | Moulding table, Moulding equipments | 2 Nos. |

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(R 2021) Semester – IV

MR3461 SENSORS AND INSTRUMENTATION LABORATORY

| Sl.No. | Description of Equipment | Required Numbers |
|---------------|---|-------------------------|
| 1. | Load, Torque and Force using Strain Gauge Measurement setup | Each -1 |
| 2. | Pressure Sensor and Piezoelectric Force Sensor Measurement setup | Each 1 |
| 3. | LVDT setup | 1 |
| 4. | Temperature Sensors measurement setup with RTD, Thermocouple and Thermistor | Each 1 |
| 5. | Measurement setup Optical Sensors LDR, Photo transistor, photo diode | Each 1 |
| 6. | Measurement setup -Ultrasonic and Laser Sensor | Each 1 |
| 7. | Gyroscope measurement setup | 1 |
| 8. | Accelerometer measurement setup | 1 |
| 9. | Magnetometer measurement setup | 1 |
| 10. | Absolute Encoders and Incremental encoder with DSO/ single board computer | Each 1 |
| 11. | DAQ with sensor or transducer | 1 |
| 12. | 3 axis force sensor with measurement setup | 1 |
| 13. | Tactile Sensor with touch measurement setup | 1 |

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MR3492 EMBEDDED SYSTEMS AND PROGRAMMING (LABORATORY)

| Sl.No. | Description of Equipment | Required Numbers |
|---------------|---|-------------------------|
| 1. | Computers | 15 |
| 2. | 8051 trainer kit interfaced with above computers | 2 |
| 3. | Alphanumeric and Graphic LCD Interfacing interfaced with 8051 | 1 Each |
| 4. | Switches and keyboard interfacing of 8051. | 1 Each |
| 5. | Sensor Interfacing with ADC to 8051 and DAC & RTC Interfacing with 8051 kit | 1 Each |
| 6. | UART Serial and Parallel Port with 8051 kit | 1 Each |
| 7. | I ² C, SPI and CAN protocols with 8051 kit | 1 Each |
| 8. | Step Motor (Unipolar & Bipolar Motor) and PWM Servo Motor Control to Interfacing with 8051 kit | 1 each |
| 9. | Interfacing and Programming of Bluetooth and Wi-Fi with 8051 kit | 1 each |
| 10. | ARM Processor– kit/development boards- 2 nos with WIFI module, Sensors, Stepper motor and servomotor – 1 each | 1 Set |
| 11. | Single board computer (Raspberry PI/ any other open source boards) with internet provision and open source IOT service provider setup | 1 set |
| 12. | Software for 8051 programming | 15 No's |

Any 7 equipment with the combination 8051, ARM and Single board computers is recommended

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MR3561 INDUSTRIAL AUTOMATION LABORATORY

| Sl.No. | Description of Equipment | Required Numbers |
|--|--|-------------------------|
| Hydraulic Equipment | | |
| 1. | Pressure relief valve | 4 |
| 2. | Pressure reducing valves | 2 |
| 3. | Flow control valves | 2 |
| 4. | Pressure switch | 1 |
| 5. | Limit switches | 2 |
| 6. | Linear actuator | 1 |
| 7. | Rotary actuator | 1 |
| 8. | Double solenoid actuated DCV | 1 |
| 9. | Single solenoid actuated DCV | 1 |
| 10. | Hydraulic power pack with pump and pressure relief valve | 1 |
| 11. | PLC with hydraulic interface | 1 set |
| Pneumatics Equipment | | |
| 1. | Pneumatic trainer kit with FRL Unit, Single acting cylinder, push button | 1 |
| 2. | Pneumatic training kit with FRL unit, Double acting cylinder, manually actuated DCV | 1 |
| 3. | Pneumatic trainer kit with FRL unit, Double acting cylinder, Pilot actuated DCV | 1 |
| 4. | Pneumatic trainer kit with FRL unit Double acting cylinder, Double solenoid actuated DCV, DCV with sensor / magnetic reed switches | 1 |
| 5. | PLC with Pneumatic Interface. | 1 |
| Industrial Automation Equipment | | |
| 1. | PLC to PLC communication station IOs with sensors and actuators. | 1 set |
| 2. | <ul style="list-style-type: none"> • Bottle Filling System. • Material Filling • Object Sorting • Orientation Check • Material Property Check. • Material Handling, Delaying Conveyor, Feeding, Pick and Place Operation | Each 1 No. |

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(R 2021) Semester – VI

RA3611 ROBOT KINEMATICS AND DYNAMICS LABORATORY

| Sl. No. | Description of Equipment | Required Numbers |
|----------------|--|-------------------------|
| 1 | PC workstation | 15 |
| 2 | Robot Analyser (open source) installed on computer | 15 |
| 3 | ROS with Gazebo/ moveit /v-rep installed on computer | 15 |
| 4 | Robot | 1 |

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(R 2021) Semester – VII

RA3711 ROBOTIC VISION AND INTELLIGENCE LABORATORY

| Sl.No. | Description of Equipment | Required Numbers |
|---------------|---|-------------------------|
| 1 | Camera with lenses and camera mounting interfaced with PC/any system | 5 |
| 2 | Camera with any single board computers (system on chip models) | 5 |
| 3 | OpenCV/ python with supported library/ licensed image processing software | 10 |